

# ELC 4351: Digital Signal Processing

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# The z-Transform and Its Application to the Analysis of LTI Systems

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# The z-Transform and Its Application to the Analysis of LTI Systems

Laplace-Transform: Continuous-time signals and LTI systems

z-Transform: Discrete-time signals and LTI systems

# The Direct z-Transform

The direct z-transform is a power series.

## Transform Equation

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

where,  $z$  is a complex variable.

It can be expressed as  $X(z) = \mathcal{Z}\{x(n)\}$  or  $x(n) \longleftrightarrow^z X(z)$ .

The region of convergence (ROC) of  $X(z)$  is the set of all values of  $z$  for which  $X(z)$  attains a finite value.

# Discussion on ROC

$z = re^{j\theta}$ .  $r = |z|$  and  $\theta = \angle z$ .

## Transformation Equation

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)r^{-n}e^{-j\theta n}$$

In the ROC,  $|X(z)| < \infty$ .

Therefore

$$\begin{aligned}|X(z)| &= \left| \sum_{n=-\infty}^{\infty} x(n)r^{-n}e^{-j\theta n} \right| \\ &\leq \sum_{n=-\infty}^{\infty} |x(n)r^{-n}e^{-j\theta n}| \\ &= \sum_{n=-\infty}^{\infty} |x(n)r^{-n}|\end{aligned}$$

# Discussion on ROC

$$|X(z)| \leq \sum_{n=-\infty}^{\infty} |x(n)r^{-n}| < \infty$$

$|X(z)|$  is finite if the sequence  $x(n)r^{-n}$  is absolutely summable.

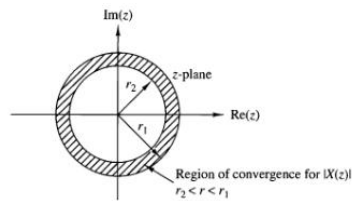
# Discussion on ROC

$$\begin{aligned} |X(z)| &\leq \sum_{n=-\infty}^{\infty} |x(n)r^{-n}| \\ &= \sum_{n=-\infty}^{-1} |x(n)r^{-n}| + \sum_{n=0}^{\infty} |x(n)r^{-n}| \\ &= \underbrace{\sum_{n=1}^{\infty} |x(-n)r^n|}_{\text{finite: } r \text{ small enough}} + \underbrace{\sum_{n=0}^{\infty} \left| \frac{x(n)}{r^n} \right|}_{\text{finite: } r \text{ large enough}} \end{aligned}$$

In general, ROC:  $r_2 < r < r_1$

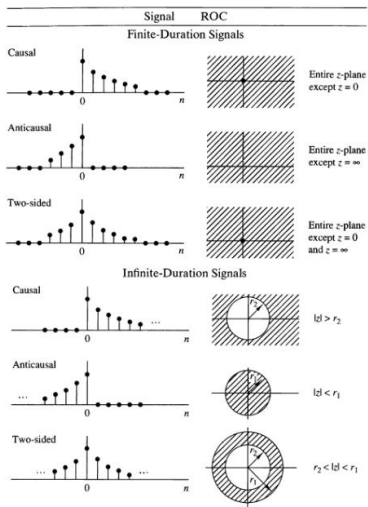
# Discussion on ROC

ROC:  $r_2 < r < r_1$





# Discussion on ROC



## Transformation Equation

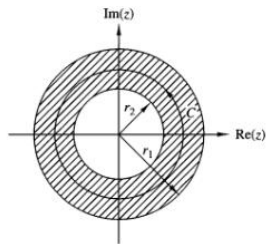
$$X^+(z) = \sum_{n=0}^{\infty} x(n)z^{-n}$$

# The Inverse z-Transform

## Transformation Equation

$$x(n) = \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz$$

where  $C$  denotes the closed contour in the ROC of  $X(z)$ , taken in a counterclockwise direction.



# Properties of the z-Transform

## Linearity

If  $x_1(n) \longleftrightarrow^z X_1(z)$  and  $x_2(n) \longleftrightarrow^z X_2(z)$ , then

$$x(n) = \alpha_1 x_1(n) + \alpha_2 x_2(n) \longleftrightarrow^z X(z) = \alpha_1 X_1(z) + \alpha_2 X_2(z)$$

for any constants  $\alpha_1$  and  $\alpha_2$ .

## Time shifting

If  $x(n) \longleftrightarrow^z X(z)$ , then

$$x(n - k) \longleftrightarrow^z z^{-k} X(z)$$

The ROC of  $z^{-k} X(z)$  is the same as that of  $X(z)$  except for  $z = 0$  if  $k > 0$  and  $z = \infty$  if  $k < 0$ .

# Properties of the z-Transform

## Scaling in the z-domain

If  $x(n) \longleftrightarrow^z X(z)$ , ROC:  $r_1 < |z| < r_2$ , then

$$a^n x(n) \longleftrightarrow^z X(a^{-1}z), \quad \text{ROC: } |a|r_1 < |z| < |a|r_2$$

for any constants  $a$ , real or complex.

## Time reversal

If  $x(n) \longleftrightarrow^z X(z)$ , ROC:  $r_1 < |z| < r_2$ , then

$$x(-n) \longleftrightarrow^z X(z^{-1}), \quad \text{ROC: } \frac{1}{r_2} < |z| < \frac{1}{r_1}$$

## Differentiation in the z-domain

If  $x(n) \longleftrightarrow^z X(z)$ , then

$$nx(n) \longleftrightarrow^z -z \frac{dX(z)}{dz}$$

# Properties of the z-Transform

## Convolution of two sequences

If  $x_1(n) \longleftrightarrow^z X_1(z)$  and  $x_2(n) \longleftrightarrow^z X_2(z)$ , then

$$x(n) = x_1(n) \otimes x_2(n) \longleftrightarrow^z X(z) = X_1(z)X_2(z)$$

The ROC of  $X(z)$  is at least the intersection of that for  $X_1(z)$  and  $X_2(z)$ .

## Correlation of two sequences

If  $x_1(n) \longleftrightarrow^z X_1(z)$  and  $x_2(n) \longleftrightarrow^z X_2(z)$ , then

$$r_{x_1x_2}(l) = \sum_{n=-\infty}^{\infty} x_1(n)x_2(n-l) \longleftrightarrow^z R_{x_1x_2}(z) = X_1(z)X_2(z^{-1})$$

The ROC of  $R(z)$  is at least the intersection of that for  $X_1(z)$  and  $X_2(z^{-1})$ .

## Multiplication of two sequences

If  $x_1(n) \longleftrightarrow^z X_1(z)$  and  $x_2(n) \longleftrightarrow^z X_2(z)$ , then

$$x(n) = x_1(n)x_2(n) \longleftrightarrow^z X(z) = \frac{1}{2\pi j} \oint_C X_1(\nu)X_2\left(\frac{z}{\nu}\right)\nu^{-1}d\nu$$

where  $C$  is a closed contour that encloses the origin and lies within the ROC common to both  $X_1(\nu)$  and  $X_2(1/\nu)$ .



# Properties of the z-Transform

## Parseval's relation

If  $x_1(n)$  and  $x_2(n)$  are complex-valued sequences, then

$$\sum_{n=-\infty}^{\infty} x_1(n)x_2^*(n) = \frac{1}{2\pi j} \oint_C X_1(\nu)X_2^*\left(\frac{1}{\nu^*}\right)\nu^{-1}d\nu$$

## The Initial Value Theorem

If  $x(n)$  is causal, i.e.  $x(n) = 0$  for  $n < 0$ , then

$$x(0) = \lim_{z \rightarrow \infty} X(z)$$

Proof.

$$\begin{aligned} X(z) &= \sum_{n=0}^{\infty} x(n)z^{-n} \\ &= x(0) + x(1)z^{-1} + x(2)z^{-2} + \dots \end{aligned}$$

As  $z \rightarrow \infty$ ,  $z^{-n} \rightarrow 0$  when  $n = 1, 2, \dots$ , therefore  $X(z) \rightarrow x(0)$ .